



# ORF 307: Lecture 4

## Linear Programming: Chapter 3 Degeneracy

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# Solve This...

$$\begin{array}{ll}\text{maximize} & 2x_1 + 3x_2 \\ \text{subject to} & x_1 + 2x_2 \leq 8 \\ & x_1 - x_2 \leq 4 \\ & -x_1 + x_2 \leq 4 \\ & x_1, x_2 \geq 0.\end{array}$$

# Solution

$$\text{maximize } \zeta = 0 + 2x_1 + 3x_2$$

$$w_1 = 8 - 1x_1 - 2x_2$$

$$w_2 = 4 - 1x_1 - 1x_2$$

$$w_3 = 4 - 1x_1 - 1x_2$$

⇓ Enter:  $x_2$ , Leave:  $w_3$

$$\text{maximize } \zeta = 12 + 5x_1 - 3w_3$$

$$w_1 = 0 - 3x_1 - 2w_3$$

$$w_2 = 8 - 0x_1 - 1w_3$$

$$x_2 = 4 - 1x_1 - 1w_3$$

⇓ Enter:  $x_1$ , Leave:  $w_1$

$$\text{maximize } \zeta = 12 - \frac{5}{3}w_1 + \frac{1}{3}w_3$$

$$x_1 = 0 - \frac{1}{3}w_1 - \frac{2}{3}w_3$$

$$w_2 = 8 - 0w_1 - 1w_3$$

$$x_2 = 4 - \frac{1}{3}w_1 - \frac{1}{3}w_3$$

⇓ Enter:  $w_3$ , Leave:  $w_2$

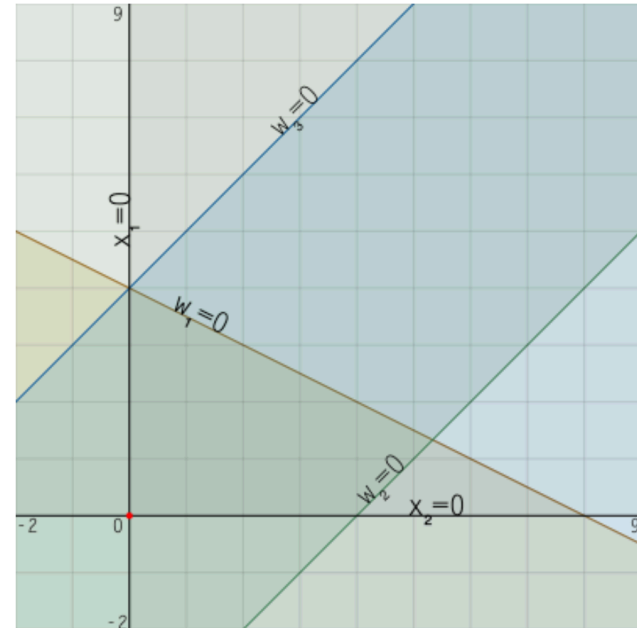
$$\text{maximize } \zeta = \frac{44}{3} - \frac{5}{3}w_1 - \frac{1}{3}w_2$$

$$x_1 = \frac{16}{3} - \frac{1}{3}w_1 - \frac{2}{3}w_2$$

$$w_3 = 8 - 0w_1 - 1w_2$$

$$x_2 = \frac{4}{3} - \frac{1}{3}w_1 - \frac{1}{3}w_2$$

Note: The horizontal axis, which one might call the  $x_1$ -axis, is where  $x_2 = 0$  and is labeled as such.



In  $(x_1, x_2)$  coordinates, the pivots visit the following vertices:

$$(0, 0) \Rightarrow (0, 1) \Rightarrow (4/3, 1/3)$$

Note that the second pivot went nowhere. 2

# Degeneracy

## Definitions.

A *dictionary is degenerate* if one or more “rhs”-value vanishes.

Example:

$$\begin{array}{rcllcll} \zeta & = & 6 & + & w_3 & + & 5x_2 & + & 4w_1 \\ \hline x_3 & = & 1 & - & 2w_3 & - & 2x_2 & + & 3w_1 \\ w_2 & = & 4 & + & w_3 & + & x_2 & - & 3w_1 \\ x_1 & = & 3 & - & 2w_3 & & & & \\ w_4 & = & 2 & + & w_3 & & & - & w_1 \\ w_5 & = & 0 & & & - & x_2 & + & w_1 \end{array}$$

A *pivot is degenerate* if the objective function value does not change.

Examples (based on above dictionary):

1. If  $x_2$  enters, then  $w_5$  must leave, pivot is degenerate.
2. If  $w_1$  enters, then  $w_2$  must leave, pivot is *not* degenerate.

# Cycling

A *cycle* is a sequence of pivots that returns to the dictionary from which the cycle began.

Note: Every pivot in a cycle must be degenerate. Why?

## Pivot Rules

A *pivot rule* is an explicit statement for how one chooses entering and leaving variables (when a choice exists).

Some Examples:

*Largest-Coefficient Rule.* (most common pivot rule for entering variable)

Choose the variable with the largest coefficient in the objective function.

*Random Positive-Coefficient Rule.*

Among all nonbasic variables having a positive coefficient, choose one at random.

*First Encountered Rule.*

In scanning the nonbasic variables, stop with the first one whose coefficient is positive.

# Hope

Some pivot rule, such as the largest coefficient rule, will be proven never to cycle.

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## Hope Fades

An example that cycles using the following pivot rules:

- entering variable: largest-coefficient rule.
- leaving variable: smallest-index rule.

$$\begin{array}{rcllclclcl} \zeta & = & & x_1 & - & 2x_2 & & - & 2x_4 \\ \hline w_1 & = & - & 0.5x_1 & + & 3.5x_2 & + & 2x_3 & - & 4x_4 \\ w_2 & = & - & 0.5x_1 & + & x_2 & + & 0.5x_3 & - & 0.5x_4 \\ w_3 & = & 1 & - & x_1 & . & & & & \end{array}$$

Here's a demo of cycling (ignoring the last constraint)...

$$\begin{aligned}\zeta &= 0 + 1 x_1 + -2 x_2 + 0 x_3 + -2 x_4 \\ w_1 &= 0 - 1/2 x_1 - -7/2 x_2 - -2 x_3 - 4 x_4 \\ w_2 &= 0 - 1/2 x_1 - -1 x_2 - -1/2 x_3 - 1/2 x_4\end{aligned}$$

⇓ Enter:  $x_1$ , Leave:  $w_1$

$$\begin{aligned}\zeta &= 0 + -2 w_1 + 5 x_2 + 4 x_3 + -10 x_4 \\ x_1 &= 0 - 2 w_1 - -7 x_2 - -4 x_3 - 8 x_4 \\ w_2 &= 0 - -1 w_1 - 5/2 x_2 - 3/2 x_3 - -7/2 x_4\end{aligned}$$

⇓ Enter:  $x_2$ , Leave:  $w_2$

$$\begin{aligned}\zeta &= 0 + 0 w_1 + -2 w_2 + 1 x_3 + -3 x_4 \\ x_1 &= 0 - -4/5 w_1 - 14/5 w_2 - 1/5 x_3 - -9/5 x_4 \\ x_2 &= 0 - -2/5 w_1 - 2/5 w_2 - 3/5 x_3 - -7/5 x_4\end{aligned}$$

⇓ Enter:  $x_3$ , Leave:  $x_1$

$$\begin{aligned}\zeta &= 0 + 4 w_1 + -16 w_2 + -5 x_1 + 6 x_4 \\ x_3 &= 0 - -4 w_1 - 14 w_2 - 5 x_1 - -9 x_4 \\ x_2 &= 0 - 2 w_1 - -8 w_2 - -3 x_1 - 4 x_4\end{aligned}$$

⇓ Enter:  $x_4$ , Leave:  $x_2$



$$\begin{aligned}
 \zeta &= 0 + 1 w_1 + -4 w_2 + -1/2 x_1 + -3/2 x_2 \\
 x_3 &= 0 - 1/2 w_1 - -4 w_2 - -7/4 x_1 - 9/4 x_2 \\
 x_4 &= 0 - 1/2 w_1 - -2 w_2 - -3/4 x_1 - 1/4 x_2
 \end{aligned}$$

⇓ Enter:  $w_1$ , Leave:  $x_3$

$$\begin{aligned}
 \zeta &= 0 + -2 x_3 + 4 w_2 + 3 x_1 + -6 x_2 \\
 w_1 &= 0 - 2 x_3 - -8 w_2 - -7/2 x_1 - 9/2 x_2 \\
 x_4 &= 0 - -1 x_3 - 2 w_2 - 1 x_1 - -2 x_2
 \end{aligned}$$

⇓ Enter:  $w_2$ , Leave:  $x_4$

$$\begin{aligned}
 \zeta &= 0 + 0 x_3 + -2 x_4 + 1 x_1 + -2 x_2 \\
 w_1 &= 0 - -2 x_3 - 4 x_4 - 1/2 x_1 - -7/2 x_2 \\
 w_2 &= 0 - -1/2 x_3 - 1/2 x_4 - 1/2 x_1 - -1 x_2
 \end{aligned}$$

*Cycling is rare for small problems!* A program that generates random  $2 \times 4$  fully degenerate problems was run more than *one billion* times and did not find one example!

However, for larger problems with lots of zeros, cycling is common and can be a real problem.

# Algebra of a Pivot

$b$	$a$	
$d$	$c$	

$\xrightarrow{\text{pivot}}$

$-\frac{b}{a}$	$\frac{1}{a}$	
$d - \frac{bc}{a}$	$\frac{c}{a}$	

# AMPL Code

```
param m := 2;
param n := 4;

param c {1..n};      param A {1..m, 1..n};
param nonbasics {1..n}; param basics {1..m};
param row;           param col;
param ii;            param jj;
param Arow {1..n};   param Acol {1..m};
param cj;            param bi;
param a;             param ccol;
param iter;

for {k in 1..1000000000} {
  let {i in 1..m, j in 1..n} A[i,j] := Normal01();
  let {j in 1..n} c[j] := Normal01();
  let {j in 1..n} nonbasics[j] := j;
  let {i in 1..m} basics[i] := n+i;
  display k;

  let iter := 1;
  repeat while (max {j in 1..n} c[j] > 0) {
    let cj := 0;
    for {j in 1..n} {
      if (c[j] > cj) then {
        let col := j;
        let cj := c[j];
      }
    }
    let jj := nonbasics[col];

    let bi := m+n+1;
    for {i in 1..m: A[i,jj] < -1e-8} {
      if (basics[i] < bi) then {
        let bi := basics[i];
        let row := i;
      }
    }

    if bi > m+n then {break;} # unbounded polytope
    let ii := basics[row];
```

```
let {j in 1..n} Arow[j] := A[row,j];
let {i in 1..m} Acol[i] := A[i,col];
let a := A[row,col];

let {i in 1..m, j in 1..n}
  A[i,j] := A[i,j] - Acol[i]*Arow[j]/a;
let {j in 1..n} A[row,j] := -Arow[j]/a;
let {i in 1..m} A[i,col] := Acol[i]/a;
let A[row,col] := 1/a;

let ccol := c[col];
let {j in 1..n} c[j] := c[j] - ccol*Arow[j]/a;
let c[col] := ccol/a;

let basics[row] := jj;
let nonbasics[col] := ii;

if iter > 15 then {
  display "found a cycling example";
  break;
}

let iter := iter+1;
```

```
}
}
```

# Perturbation Method

Whenever a vanishing “rhs” appears perturb it.  
If there are lots of them, say  $k$ , perturb them all.  
Make the perturbations at different *scales*:

$$\text{other data} \gg \epsilon_1 \gg \epsilon_2 \gg \cdots \gg \epsilon_k > 0.$$

*An Example.*

$$\begin{aligned}\zeta &= 0 + 0\epsilon_1 + 0\epsilon_2 + 0\epsilon_3 + 2x_1 + 4x_2 \\ w_1 &= 0 + 1\epsilon_1 + 0\epsilon_2 + 0\epsilon_3 - 1x_1 - 1x_2 \\ w_2 &= 0 + 0\epsilon_1 + 1\epsilon_2 + 0\epsilon_3 - 3x_1 - 1x_2 \\ w_3 &= 0 + 0\epsilon_1 + 0\epsilon_2 + 1\epsilon_3 - 4x_1 - 1x_2\end{aligned}$$

Entering variable:  $x_2$

Leaving variable:  $w_2$

$$\begin{aligned}\zeta &= 0 + 0\epsilon_1 + 4\epsilon_2 + 0\epsilon_3 + 14x_1 - 4w_2 \\ w_1 &= 0 + 1\epsilon_1 - 1\epsilon_2 + 0\epsilon_3 - 2x_1 - 1w_2 \\ x_2 &= 0 + 0\epsilon_1 + 1\epsilon_2 + 0\epsilon_3 - 3x_1 - 1w_2 \\ w_3 &= 0 + 0\epsilon_1 + 1\epsilon_2 + 1\epsilon_3 - 1x_1 - 1w_2\end{aligned}$$

# Perturbation Method—Example Con't.

Recall current dictionary:

$$\begin{aligned}\zeta &= 0 + 0 \epsilon_1 + 4 \epsilon_2 + 0 \epsilon_3 + 14 x_1 + (-4) w_2 \\ w_1 &= 0 + 1 \epsilon_1 + (-1) \epsilon_2 + 0 \epsilon_3 - 2 x_1 - (-1) w_2 \\ x_2 &= 0 + 0 \epsilon_1 + 1 \epsilon_2 + 0 \epsilon_3 - (-3) x_1 - 1 w_2 \\ w_3 &= 0 + 0 \epsilon_1 + 1 \epsilon_2 + 1 \epsilon_3 - 1 x_1 - 1 w_2\end{aligned}$$

Entering variable:  $x_1$

Leaving variable:  $w_3$

$$\begin{aligned}\zeta &= 0 + 0 \epsilon_1 + 18 \epsilon_2 + 14 \epsilon_3 + (-14) w_3 + (-18) w_2 \\ w_1 &= 0 + 1 \epsilon_1 + (-3) \epsilon_2 + (-2) \epsilon_3 - (-2) w_3 - (-3) w_2 \\ x_2 &= 0 + 0 \epsilon_1 + 4 \epsilon_2 + 3 \epsilon_3 - 3 w_3 - 4 w_2 \\ x_1 &= 0 + 0 \epsilon_1 + 1 \epsilon_2 + 1 \epsilon_3 - 1 w_3 - 1 w_2\end{aligned}$$

DONE!

# Perturbation Method Applied to Cycling Example

$$\begin{aligned}\zeta &= 0 + 0 \epsilon_1 + 0 \epsilon_2 + 1 x_1 + -2 x_2 + 0 x_3 + -2 x_4 \\ w_1 &= 0 + 1 \epsilon_1 + 0 \epsilon_2 - 1/2 x_1 - -1 x_2 - -1/2 x_3 - 1/2 x_4 \\ w_2 &= 0 + 0 \epsilon_1 + 1 \epsilon_2 - 1/2 x_1 - -7/2 x_2 - -2 x_3 - 4 x_4\end{aligned}$$

⇓  $x_1$  enters,  $w_2$  leaves

$$\begin{aligned}\zeta &= 0 + 0 \epsilon_1 + 2 \epsilon_2 + -2 w_2 + 5 x_2 + 4 x_3 + -10 x_4 \\ w_1 &= 0 + 1 \epsilon_1 + -1 \epsilon_2 - -1 w_2 - 5/2 x_2 - 3/2 x_3 - -7/2 x_4 \\ x_1 &= 0 + 0 \epsilon_1 + 2 \epsilon_2 - 2 w_2 - -7 x_2 - -4 x_3 - 8 x_4\end{aligned}$$

⇓  $x_2$  enters,  $w_1$  leaves

$$\begin{aligned}\zeta &= 0 + 2 \epsilon_1 + 0 \epsilon_2 + 0 w_2 + -2 w_1 + 1 x_3 + -3 x_4 \\ x_2 &= 0 + 2/5 \epsilon_1 + -2/5 \epsilon_2 - -2/5 w_2 - 2/5 w_1 - 3/5 x_3 - -7/5 x_4 \\ x_1 &= 0 + 14/5 \epsilon_1 + -4/5 \epsilon_2 - -4/5 w_2 - 14/5 w_1 - 1/5 x_3 - -9/5 x_4\end{aligned}$$

⇓  $x_3$  enters,  $x_2$  leaves

$$\begin{aligned}\zeta &= 0 + 8/3 \epsilon_1 + -2/3 \epsilon_2 + 2/3 w_2 + -8/3 w_1 + -5/3 x_2 + -2/3 x_4 \\ x_3 &= 0 + 2/3 \epsilon_1 + -2/3 \epsilon_2 - -2/3 w_2 - 2/3 w_1 - 5/3 x_2 - -7/3 x_4 \\ x_1 &= 0 + 8/3 \epsilon_1 + -2/3 \epsilon_2 - -2/3 w_2 - 8/3 w_1 - -1/3 x_2 - -4/3 x_4\end{aligned}$$

⇓  $w_2$  enters, problem unbounded!

Note: objective function increases with every pivot:  $0 < 2\epsilon_2 < 2\epsilon_1 < \frac{8}{3}\epsilon_1 - \frac{2}{3}\epsilon_2$

# Other Pivot Rules

## *Smallest Index Rule.*

Choose the variable with the smallest index (the  $x$  variables are assumed to be “before” the  $w$  variables).

Note: Also known as *Bland's rule*.

No cycling (it's been proved).

## *Random Selection Rule.*

Select at random from the set of possibilities.

No infinite cycles.

## *Greatest Increase Rule.*

Pick the entering/leaving pair so as to maximize the increase of the objective function over all other possibilities.

Note: Too much computation.

Needs a tie-breaking rule.

# Theoretical Results

*Cycling Theorem.* If the simplex method fails to terminate, then it must cycle.

Why?

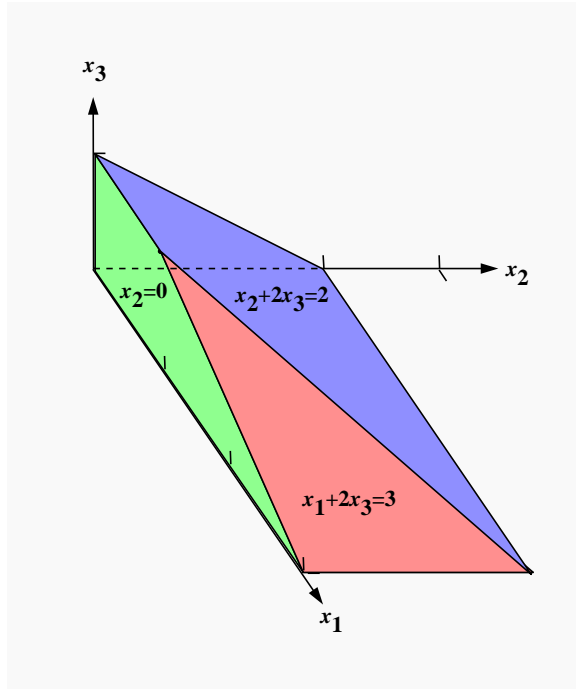
*Fundamental Theorem of Linear Programming.* For an arbitrary linear program in standard form, the following statements are true:

1. If there is no optimal solution, then the problem is either infeasible or unbounded.
2. If a feasible solution exists, then a basic feasible solution exists.
3. If an optimal solution exists, then a basic optimal solution exists.



# Geometry

$$\begin{array}{ll}
 \text{maximize} & x_1 + 2x_2 + 3x_3 \\
 \text{subject to} & x_1 + 2x_3 \leq 3 \\
 & x_2 + 2x_3 \leq 2 \\
 & x_1, x_2, x_3 \geq 0
 \end{array}$$



$$\begin{array}{ll}
 \text{maximize} & x_1 + 2x_2 + 3x_3 \\
 \text{subject to} & x_1 + 2x_3 \leq 2 \\
 & x_2 + 2x_3 \leq 2 \\
 & x_1, x_2, x_3 \geq 0
 \end{array}$$

