## The ParametričSelf-Dual Simplex Method Revisited



## My Congrats to Robert Freund

To Rob:

- It is great that you have been here on Earth for 70 years.


## My Congrats to Robert Freund

To Rob:

- It is great that you have been here on Earth for 70 years.
- And at MIT for 40 years.


## My Congrats to Robert Freund

To Rob:

- It is great that you have been here on Earth for 70 years.
- And at MIT for 40 years.
- It's been really fun hanging out with you at conferences all around the world.


## My Congrats to Robert Freund

To Rob:

- It is great that you have been here on Earth for 70 years.
- And at MIT for 40 years.
- It's been really fun hanging out with you at conferences all around the world.
- I'm hoping that maybe we can someday visit Mars together.

To Rob:

- It is great that you have been here on Earth for 70 years.
- And at MIT for 40 years.
- It's been really fun hanging out with you at conferences all around the world.
- I'm hoping that maybe we can someday visit Mars together.

To everyone else:

- Rob and I both served as Chairs of the INFORMS Optimization Section (1999-2002).

To Rob:

- It is great that you have been here on Earth for 70 years.
- And at MIT for 40 years.
- It's been really fun hanging out with you at conferences all around the world.
- I'm hoping that maybe we can someday visit Mars together.

To everyone else:

- Rob and I both served as Chairs of the INFORMS Optimization Section (1999-2002).
- I'm a glider pilot. I gave Rob three rides on Apr. 19, 1993. The third one was really really good-released from tow at 4000 feet and climbed to 7600 feet.


## My Congrats to Robert Freund

To Rob:

- It is great that you have been here on Earth for 70 years.
- And at MIT for 40 years.
- It's been really fun hanging out with you at conferences all around the world.
- I'm hoping that maybe we can someday visit Mars together.

To everyone else:

- Rob and I both served as Chairs of the INFORMS Optimization Section (1999-2002).
- I'm a glider pilot. I gave Rob three rides on Apr. 19, 1993. The third one was really really good-released from tow at 4000 feet and climbed to 7600 feet.
- Rob and I have been friends for 35 years. But, we've only co-authored one paper together and that was 31 years ago...

Prior Reduced Fill-in in Solving Equations in Interior Point Algorithms
John Birge, Robert Freund, Robert Vanderbei
Operations Research Letters, 1992

## Linear Optimization in "Symmetric Form"

Here's a primal problem in "standard" (aka inequality) form:

$$
\begin{array}{ll}
\operatorname{maximize} & c^{T} x \\
\text { subject to } & A x \leq b \\
& x \geq 0
\end{array}
$$

## Linear Optimization in "Symmetric Form"

Here's a primal problem in "standard" (aka inequality) form:

$$
\begin{array}{ll}
\operatorname{maximize} & c^{T} x \\
\text { subject to } & A x \leq b \\
& x \geq 0
\end{array}
$$

Here's it's dual:

$$
\begin{array}{ll}
\operatorname{minimize} & b^{T} y \\
\text { subject to } & A^{T} y \geq c \\
& y \geq 0
\end{array}
$$

## Linear Optimization in "Symmetric Form"

Here's a primal problem in "standard" (aka inequality) form:

$$
\begin{array}{ll}
\operatorname{maximize} & c^{T} x \\
\text { subject to } & A x \leq b \\
& x \geq 0
\end{array}
$$

Here's it's dual:

$$
\begin{array}{ll}
\operatorname{minimize} & b^{T} y \\
\text { subject to } & A^{T} y \geq c \\
& y \geq 0
\end{array}
$$

Writing the dual in standard form, we see that it's the negative transpose of the primal problem:

$$
\begin{aligned}
-\operatorname{maximize} & -b^{T} y \\
\text { subject to } & -A^{T} y \leq-c \\
& y \geq 0
\end{aligned}
$$

## Linear Optimization in "Symmetric Form"

Here's a primal problem in "standard" (aka inequality) form:

$$
\begin{array}{ll}
\operatorname{maximize} & c^{T} x \\
\text { subject to } & A x \leq b \\
& x \geq 0
\end{array}
$$

Here's it's dual:

$$
\begin{array}{ll}
\operatorname{minimize} & b^{T} y \\
\text { subject to } & A^{T} y \geq c \\
& y \geq 0
\end{array}
$$

Writing the dual in standard form, we see that it's the negative transpose of the primal problem:

$$
\begin{aligned}
-\operatorname{maximize} & -b^{T} y \\
\text { subject to } & -A^{T} y \leq-c \\
& y \geq 0
\end{aligned}
$$

Duality $\quad$ The dual of the dual is the primal.

## Linear Optimization in "Symmetric Form"

Here's a primal problem in "standard" (aka inequality) form:

$$
\begin{array}{ll}
\operatorname{maximize} & c^{T} x \\
\text { subject to } & A x \leq b \\
& x \geq 0
\end{array}
$$

Here's it's dual:

$$
\begin{array}{ll}
\operatorname{minimize} & b^{T} y \\
\text { subject to } & A^{T} y \geq c \\
& y \geq 0
\end{array}
$$

Writing the dual in standard form, we see that it's the negative transpose of the primal problem:

$$
\begin{aligned}
- \text { maximize } & -b^{T} y \\
\text { subject to } & -A^{T} y \leq-c \\
& y \geq 0
\end{aligned}
$$

Duality $\quad$ The dual of the dual is the primal.
Weak Duality If $x$ is primal feasible and $y$ is dual feasible, then $c^{T} x \leq y^{T} A x \leq y^{T} b$.

## Linear Optimization in "Symmetric Form"

Here's a primal problem in "standard" (aka inequality) form:

$$
\begin{array}{ll}
\operatorname{maximize} & c^{T} x \\
\text { subject to } & A x \leq b \\
& x \geq 0
\end{array}
$$

Here's it's dual:

$$
\begin{array}{ll}
\operatorname{minimize} & b^{T} y \\
\text { subject to } & A^{T} y \geq c \\
& y \geq 0
\end{array}
$$

Writing the dual in standard form, we see that it's the negative transpose of the primal problem:

$$
\begin{aligned}
-\operatorname{maximize} & -b^{T} y \\
\text { subject to } & -A^{T} y \leq-c \\
& y \geq 0
\end{aligned}
$$

Duality $\quad$ The dual of the dual is the primal.
Weak Duality If $x$ is primal feasible and $y$ is dual feasible, then $c^{T} x \leq y^{T} A x \leq y^{T} b$.
Strong Duality If $x$ is optimal for the primal, then there exists a dual-feasible $y$ such that

$$
c^{T} x=b^{T} y
$$

## An Example

## Primal Problem:

maximize $-3 x_{1}+11 x_{2}+2 x_{3}$
subj. to $\begin{array}{rlrl}-x_{1} & +3 x_{2} & \leq 5 \\ 3 x_{1} & +3 x_{2} & \leq \\ & 3 x_{2}+2 x_{3} & \leq 6 \\ -3 x_{1} & & -5 x_{3} & \leq-4 \\ & x_{1}, x_{2}, x_{3} & \geq 0\end{array}$

## Dual Problem:

$$
\begin{array}{rrlll}
- \text { maximize } & -5 y_{1} & -4 y_{2} & -6 y_{3} & +4 y_{4} \\
\text { subj. to } & y_{1} & -3 y_{2} & & \\
& -3 y_{1} & -3 y_{2} & -3 y_{3} & \leq \\
& & -2 y_{3}+5 y_{4} & \leq-11 \\
& & \leq 2
\end{array}
$$

$$
y_{1}, y_{2}, y_{3}, y_{4} \geq 0
$$

## An Example

## Primal Problem:

$$
\begin{array}{rrr}
\operatorname{maximize} & -3 x_{1}+11 x_{2}+2 x_{3} \\
\text { subj. to }-x_{1}+3 x_{2} & \leq 5 \\
3 x_{1}+3 x_{2} & \leq 4 \\
& 3 x_{2}+2 x_{3} & \leq 6 \\
& -3 x_{1} & \leq-4 \\
& x_{1}, x_{2}, x_{3} & \geq 0
\end{array}
$$

## Dual Problem:

$$
\begin{aligned}
& \text {-maximize }-5 y_{1}-4 y_{2}-6 y_{3}+4 y_{4}
\end{aligned}
$$

$$
\begin{aligned}
& y_{1}, y_{2}, y_{3}, y_{4} \geq 0
\end{aligned}
$$

Written in Dictionary Form:

| $\zeta$ |  |  | $-3 x_{1}+11 x_{2}$ | $+2 x_{3}$ |  |
| ---: | :--- | ---: | ---: | ---: | ---: |
| $w_{1}$ | $=$ | 5 | $x_{1}-3 x_{2}$ |  |  |
| $w_{2}$ | $=$ | $4-3 x_{1}-3 x_{2}$ |  |  |  |
| $w_{3}$ | $=$ | 6 |  | $3 x_{2}$ |  |
| $w_{4}$ | $=$ | -4 | $+3 x_{1}$ |  |  |

Dictionary Solution:

$$
\begin{gathered}
x_{1}=0, x_{2}=0, x_{3}=0 \\
w_{1}=5, w_{2}=4, w_{3}=6, w_{4}=-4
\end{gathered}
$$

Written in Dictionary Form:

$$
\begin{array}{rlrl}
-\xi & = & -5 y_{1}-4 y_{2}-6 y_{3}+4 y_{4} \\
\hline z_{1} & =3-3 y_{1}+3 y_{2} & -3 y_{4} \\
z_{2} & =-11+3 y_{1}+3 y_{2}+3 y_{3} \\
z_{3} & =-2 & & \\
& & & \\
z_{3} & -5 y_{4}
\end{array}
$$

Dictionary Solution:

$$
\begin{gathered}
y_{1}=0, y_{2}=0, y_{3}=0, y_{4}=0, \\
z_{1}=3, z_{2}=-11, z_{3}=-2
\end{gathered}
$$

Note: Current "solution" is neither primal nor dual feasible.

## Parametric Self-Dual Simplex Method

Introduce a parameter $\mu$ and perturb:

## Primal Problem:



## Dual Problem:



Here's how the primal version looks in my online pivot tool:


$$
11 \leq \mu \leq \quad \infty
$$

For $\mu \geq 11$, dictionary is optimal. $x_{2}$ is the entering variable and $w_{2}$ is the leaving variable.

## Before and After the First Pivot




$$
\mathrm{X}_{1}, \mathrm{X}_{0}, \mathrm{X}_{2}, \quad \mathrm{w}_{1}, \mathrm{w}_{0}, \mathrm{w}_{2}, \mathrm{w}_{4} \geq 0
$$

## $11 \leq \mu \leq \quad \infty$

$\begin{aligned} & \text { maximize } \quad \zeta=44 / 3 \\ &+-4 / 3 \mu+11 / 3 \mu+-14 x_{1}+-11 / 3 w_{2}+2 \\ & x_{3}\end{aligned}$
subject to:

$$
\begin{aligned}
& x_{1}, x_{0}, x_{a}, w_{1}, w_{0}, w_{2}, w_{A} \geq 0
\end{aligned}
$$

## Before and After the Second Pivot


subject to:

$$
\mathrm{x}_{1}, \quad \mathrm{X}_{0}, \mathrm{x}_{2}, \quad \mathrm{w}_{1}, \mathrm{w}_{0}, \mathrm{w}_{2}, \mathrm{w}_{4} \geq 0
$$

## $4 \leq \mu \leq 11$


subject to:


$$
x_{1}, w_{0}, w_{4}, \quad w_{1}, x_{0}, w_{3}, x_{3} \geq 0
$$

## Before and After the Third Pivot




We're done! It's optimal.

- Freedom to pick perturbation as you like.
- Freedom to pick perturbation as you like.
- Randomizing perturbation completely solves the degeneracy problem.
- Freedom to pick perturbation as you like.
- Randomizing perturbation completely solves the degeneracy problem.
- Perturbations don't have to be "small".
- Freedom to pick perturbation as you like.
- Randomizing perturbation completely solves the degeneracy problem.
- Perturbations don't have to be "small".
- In the optimal dictionary, perturbation is completely gone-no need to remove it.
- Freedom to pick perturbation as you like.
- Randomizing perturbation completely solves the degeneracy problem.
- Perturbations don't have to be "small".
- In the optimal dictionary, perturbation is completely gone-no need to remove it.
- The average-case performance can be analyzed.
- Freedom to pick perturbation as you like.
- Randomizing perturbation completely solves the degeneracy problem.
- Perturbations don't have to be "small".
- In the optimal dictionary, perturbation is completely gone-no need to remove it.
- The average-case performance can be analyzed.
- In some real-world problems, a "natural" perturbation exists.
- Freedom to pick perturbation as you like.
- Randomizing perturbation completely solves the degeneracy problem.
- Perturbations don't have to be "small".
- In the optimal dictionary, perturbation is completely gone-no need to remove it.
- The average-case performance can be analyzed.
- In some real-world problems, a "natural" perturbation exists.

Okay, there are only 6 items in the list. SORRY.

Using only $\pm 1$ 's for the initial perturbation coefficients, the parametric self-dual simplex method used on the Klee-Minty problem takes an exponential number of pivots.

Here it is with $n=4 \ldots$

## Current Dictionary



The problem, as shown, takes $2^{n}-1=15$ pivots.
And, as usual with the Klee-Minty problem we can change the parameter coefficients so that $x_{4}$ is the first entering variable and the algorithm converges in just one pivot.

Thought experiment:

- $\mu$ starts at $\infty$.
- In reducing $\mu$, there are $n+m$ barriers.
- At each iteration, one barrier is passed-the others move about "randomly".
- To get $\mu$ to zero, we must on average pass half the barriers.
- Therefore, on average the algorithm should take $(m+n) / 2$ iterations.


## Real-World Data

| Name | $m$ | $n$ | iters | Name | $m$ | $n$ | iters |
| :--- | ---: | ---: | ---: | :--- | ---: | ---: | ---: |
| 25fv47 | 777 | 1545 | 5089 |  | nesm | 646 | 2740 |
| 5829 |  |  |  |  |  |  |  |
| 80bau3b | 2021 | 9195 | 10514 |  | recipe | 74 | 136 |
| adlittle | 53 | 96 | 141 |  | 80 |  |  |
| afiro | 25 | 32 | 16 |  | sc105 | 104 | 103 |
| sc205 | 203 | 202 | 191 |  |  |  |  |
| agg2 | 481 | 301 | 204 |  | sc50a | 49 | 48 |
| agg3 | 481 | 301 | 193 |  | sc50b | 48 | 48 |
| bandm | 224 | 379 | 1139 | 53 |  |  |  |
| beaconfd | 111 | 172 | 113 | scagr25 | 347 | 499 | 1336 |
| blend | 72 | 83 | 117 | scagr7 | 95 | 139 | 339 |
| bn11 | 564 | 1113 | 2580 | scfxm1 | 282 | 439 | 531 |
| bnl2 | 1874 | 3134 | 6381 | scfxm2 | 564 | 878 | 1197 |
| boeing1 | 298 | 373 | 619 | scfxm3 | 846 | 1317 | 1886 |
| boeing2 | 125 | 143 | 168 | scorpion | 292 | 331 | 411 |
| bore3d | 138 | 188 | 227 | scrs8 | 447 | 1131 | 783 |
| brandy | 123 | 205 | 585 | scsd1 | 77 | 760 | 172 |
| czprob | 689 | 2770 | 2635 | scsd6 | 147 | 1350 | 494 |
| d6cube | 403 | 6183 | 5883 | scsd8 | 397 | 2750 | 1548 |
| degen2 | 444 | 534 | 1421 | sctap1 | 284 | 480 | 643 |
| degen3 | 1503 | 1818 | 6398 | sctap2 | 1033 | 1880 | 1037 |
| e226 | 162 | 260 | 598 | sctap3 | 1408 | 2480 | 1339 |


| Name | $m$ | $n$ | iters | Name | $m$ | $n$ | iters |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| etamacro | 334 | 542 | 1580 | share1b | 107 | 217 | 404 |
| fffff800 | 476 | 817 | 1029 | share2b | 93 | 79 | 189 |
| finnis | 398 | 541 | 680 | shell | 487 | 1476 | 1155 |
| fit1d | 24 | 1026 | 925 | ship04l | 317 | 1915 | 597 |
| fit1p | 627 | 1677 | 15284 | ship04s | 241 | 1291 | 560 |
| forplan | 133 | 415 | 576 | ship08\| | 520 | 3149 | 1091 |
| ganges | 1121 | 1493 | 2716 | ship08s | 326 | 1632 | 897 |
| greenbea | 1948 | 4131 | 21476 | ship12\| | 687 | 4224 | 1654 |
| grow15 | 300 | 645 | 681 | ship12s | 417 | 1996 | 1360 |
| grow22 | 440 | 946 | 999 | sierra | 1212 | 2016 | 793 |
| grow7 | 140 | 301 | 322 | standata | 301 | 1038 | 74 |
| israel | 163 | 142 | 209 | standmps | 409 | 1038 | 295 |
| kb2 | 43 | 41 | 63 | stocfor1 | 98 | 100 | 81 |
| lotfi | 134 | 300 | 242 | stocfor2 | 2129 | 2015 | 2127 |
| maros | 680 | 1062 | 2998 |  |  |  |  |

Observed Data:

$$
\begin{aligned}
t & =\# \text { of iterations } \\
m & =\# \text { of constraints } \\
n & =\# \text { of variables }
\end{aligned}
$$

Model:

$$
t \approx 2^{\alpha}(m+n)^{\beta}
$$

Linearization: Take logs:

$$
\log t=\alpha \log 2+\beta \log (m+n)+\underset{\substack{\uparrow \\ \text { error }}}{\epsilon}
$$

## Parametric Self-Dual Simplex Method

Recall the thought experiment:

- $\mu$ starts at $\infty$.
- In reducing $\mu$, there are $n+m$ barriers.
- At each iteration, one barrier is passed-the others move about randomly.
- To get $\mu$ to zero, we must on average pass half the barriers.
- Therefore, on average the algorithm should take $(m+n) / 2$ iterations.

Using 69 real-world problems from the Netlib suite...
Least Squares Regression:

$$
\left[\begin{array}{l}
\bar{\alpha} \\
\bar{\beta}
\end{array}\right]=\left[\begin{array}{r}
-1.03561 \\
1.05152
\end{array}\right] \quad \Longrightarrow \quad T \approx 0.488(m+n)^{1.052}
$$

Least Absolute Deviation Regression:

$$
\left[\begin{array}{l}
\hat{\alpha} \\
\hat{\beta}
\end{array}\right]=\left[\begin{array}{r}
-0.9508 \\
1.0491
\end{array}\right] \quad \Longrightarrow \quad T \approx 0.517(m+n)^{1.049}
$$

Parametric Self-Dual Simplex Method


A $\log -\log$ plot of $T$ vs. $m+n$ and the $L^{1}$ and $L^{2}$ regression lines.

https://vanderbei.princeton.edu/307/python/psd_simplex_pivot.ipynb


## References

[1] I. Adler and N. Megiddo. A simplex algorithm whose average number of steps is bounded between two quadratic functions of the smaller dimension. Journal of the ACM, 32:871-895, 1985.
[2] J.R. Birge, R.M. Freund, and R.J. Vanderbei. Prior reduced fill-in in solving equations in interior point algorithms. $O R$ Letters, 11:195-198, 1992.
[3] K.-H. Borgwardt. The average number of pivot steps required by the simplex-method is polynomial. Zeitschrift für Operations Research, 26:157-177, 1982.
[4] G.B. Dantzig. Linear Programming and Extensions. Princeton University Press, Princeton, NJ, 1963.
[5] S.I. Gass and T. Saaty. The computational algorithm for the parametric objective function. Naval Research Logistics Quarterly, 2:39-45, 1955.
[6] C.E. Lemke. Bimatrix equilibrium points and mathematical programming. Management Science, 11:681-689, 1965.
[7] I.J. Lustig. The equivalence of Dantzig's self-dual parametric algorithm for linear programs to Lemke's algorithm. Technical Report SOL 87-4, Department of Operations Research, Stanford University, 1987.
[8] J.L. Nazareth. Homotopy techniques in linear programming. Algorithmica, 1:529-535, 1986.
[9] B. Rudloff, F. Ulus, and R.J. Vanderbei. A parametric simplex algorithm for linear vector optimization problems. Mathematical Programming, Series A, 163(1):213-242, 2017.
[10] S. Smale. On the average number of steps of the simplex method of linear programming. Mathematical Programming, 27:241-262, 1983.
[11] R.J. Vanderbei. Linear Programming: Foundations and Extensions. Springer, 4th edition, 2013.

## Thank You!

## Questions?

## Some Acknowledgements

```
5
4
6
10
3
8
7
1
1 1
9
2
```

